

Quadrature Encoder User's Manual

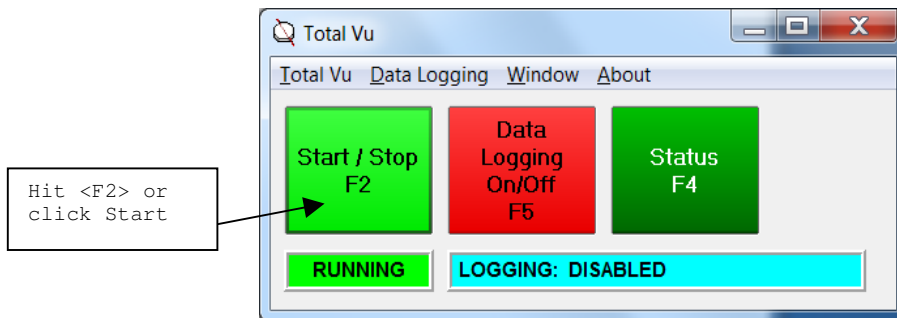
Specification and Installation Guide

NetLinc, TLAsEr400 & PTRBe

Oct 2015

This document assumes that you have already installed a NetLinc, TLAsEr400 card or PTRBe, and at least one laser micrometer—if not, please see Quick Start Guides 1-4.

NOTE: Total Vu **must be Started** or, in the **Running** state for encoder updates to occur.



Encoder Specification

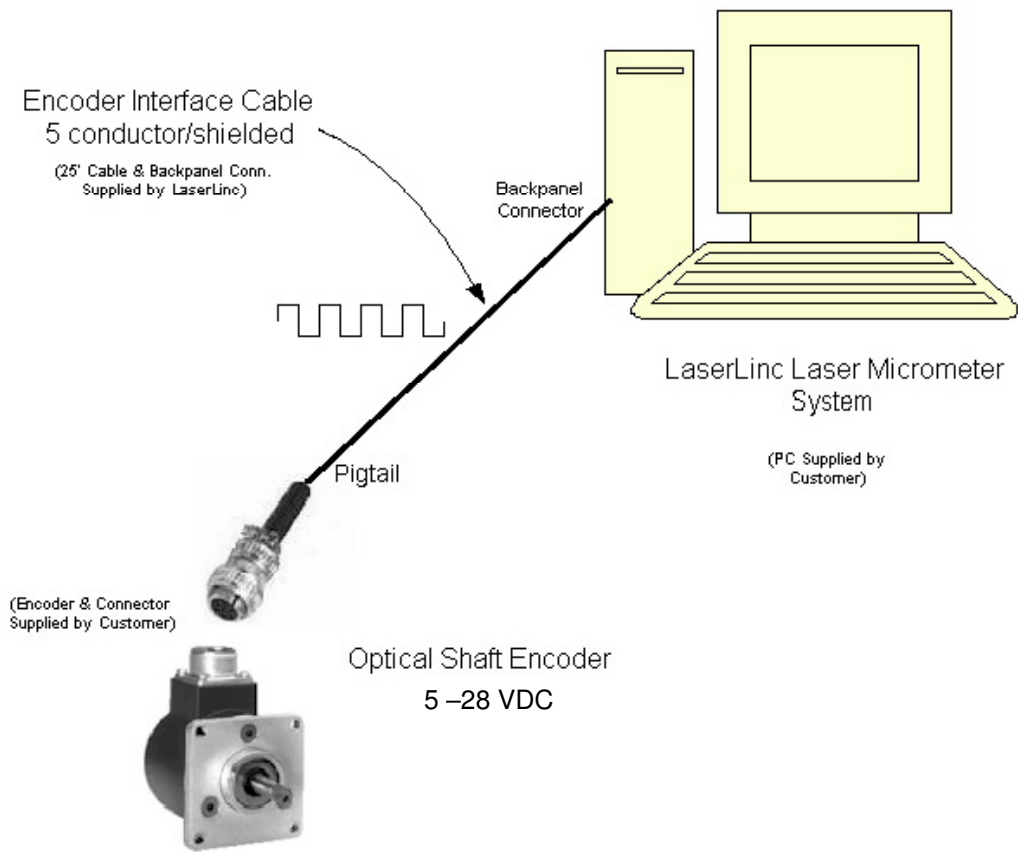
A line-speed/length encoder is a device that produces pulses to indicate line or product movement. With an encoder connected, Total Vu™ software monitors the incoming pulses to determine line speed or total product footage. Each measurement scan is then tagged with the product footage. The measurement reading and product footage pairs can be used to compute pitch measurements (see the *Total Vu User's Guide* for more information), product footage in log files, etc.

Multiple encoder inputs are possible with Total Vu. *Zero latency quadrature* inputs are available using the TLAsEr400 card(s), and/or NetLinc(s). *Non zero latency / non quadrature* counter inputs are available using an I/O device - Precision Timer Relay Box (PTRBe NetIO or PCIe version).

TABLE 2 ENCODER INTERFACE SPECIFICATION

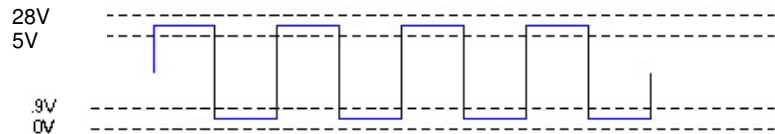
INPUT	VALUE / DESCRIPTION
Input Voltage - TLAs400/NetLinc PTRBe	4.75–28 VDC, RS-422 (factory config) - TLAs400 / NetLinc 4.75-5.25 VDC - PTRBe default. Optional 4.75–28 VDC - factory config only
Input Low Voltage Threshold	< .9V
Input High Voltage Threshold	> 1.7V
Input Impedance/Pull-up/Pull down resistors	5VDC, or 12 VDC pull-up or pull-down positions available. 2.2K ohm recommended if needed, Factory Default: - None
Input Phase - TLAs400/NetLinc PTRBe	Single Phase or Quadrature Single Phase
Input Circuit Types - TLAs400/NetLinc PTRBe	Single ended or Differential, jumper selectable, Factory Default–differential Single ended
Input Signal Type	Square wave
Maximum Frequency	1MHz
Max Cable Length	Consult your encoder manufacturer's specification
Encoder / Measurement Correlation TLAs400/NetLinc Only	Zero seconds latency between encoder sampling and measurement sampling
Encoder Interface Cable Style	Hirose, HR10A-7P-6P, provided with tinned leads
Back Panel Connector Style	Hirose, HR10A-7R-6S, provided on PC back panel
OUTPUTS	VALUE/DESCRIPTION
Encoder Supply Voltage	5 or 12 VDC for TLAs400 (Jumper J7 select), 5VDC only for NetLinc
Supply Current, fused	.150mA continuous maximum

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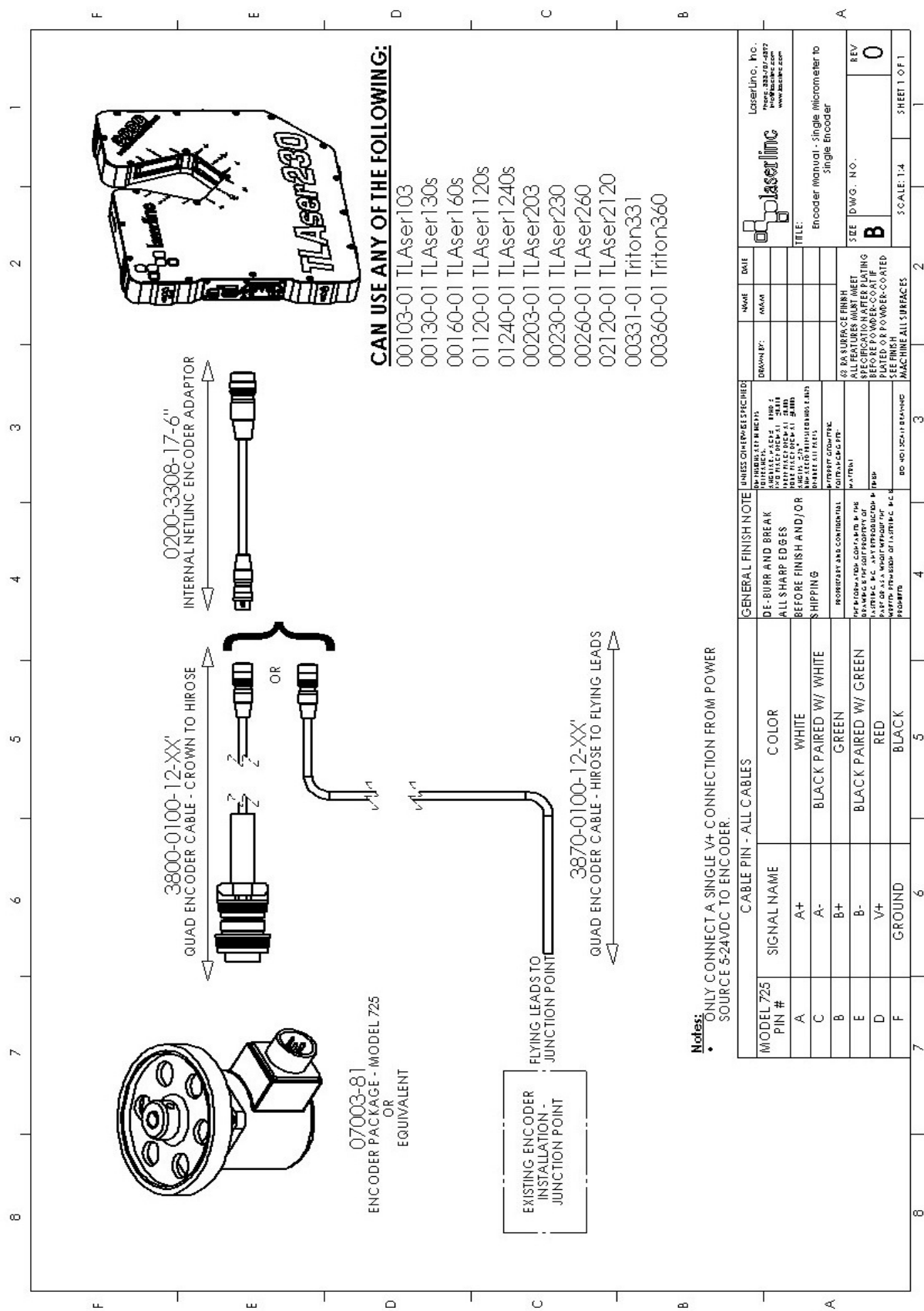


(e.g.) Encoder Products Inc. Model 725
725-NSS1000AHV1FNSYN

Typical Encoder Waveform



Typical Encoder Connector Wiring Diagram - TLAs400
Diagram 1

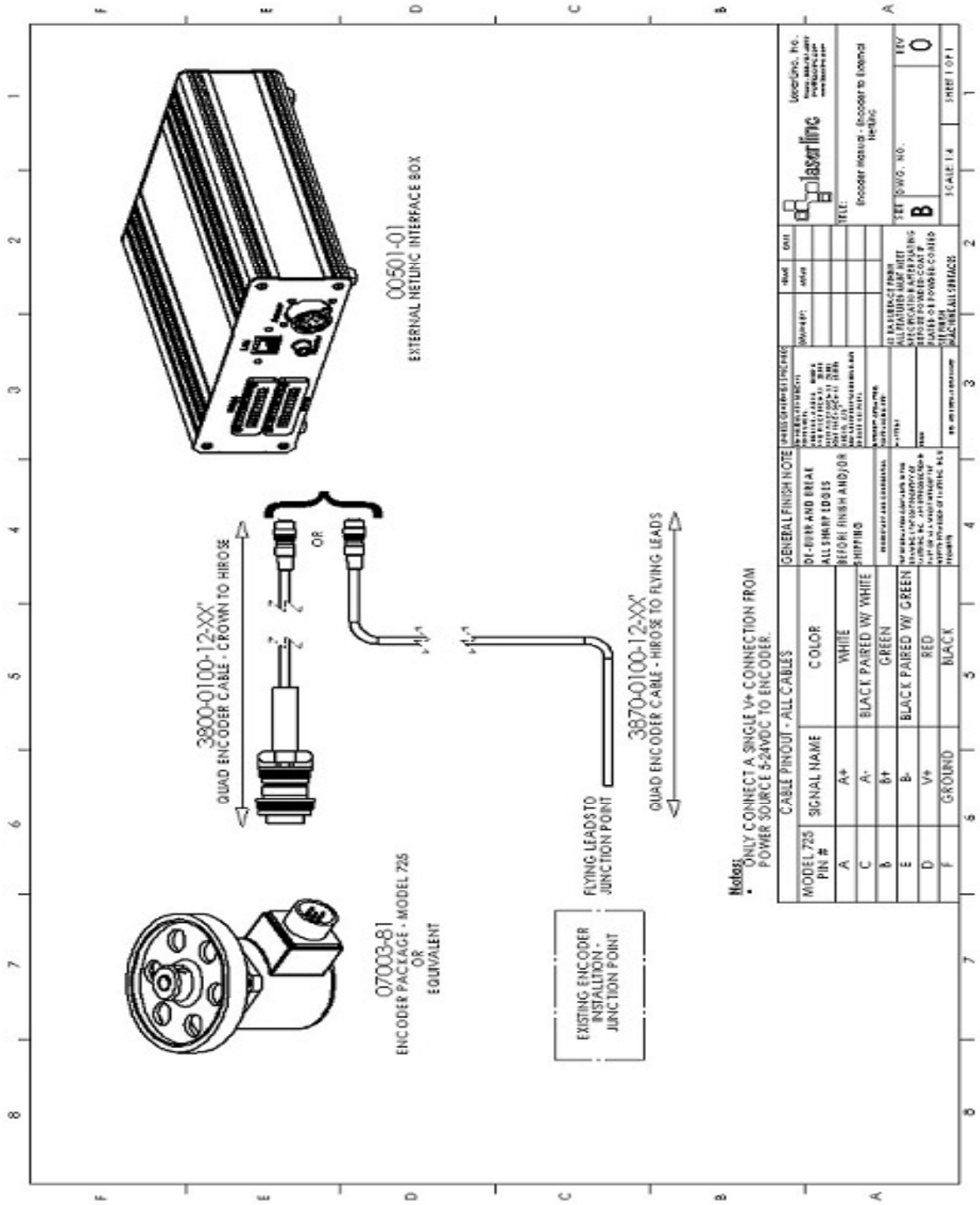


Typical Encoder Interface Wiring Diagram -Internal NetLinc(s)
Diagram 2

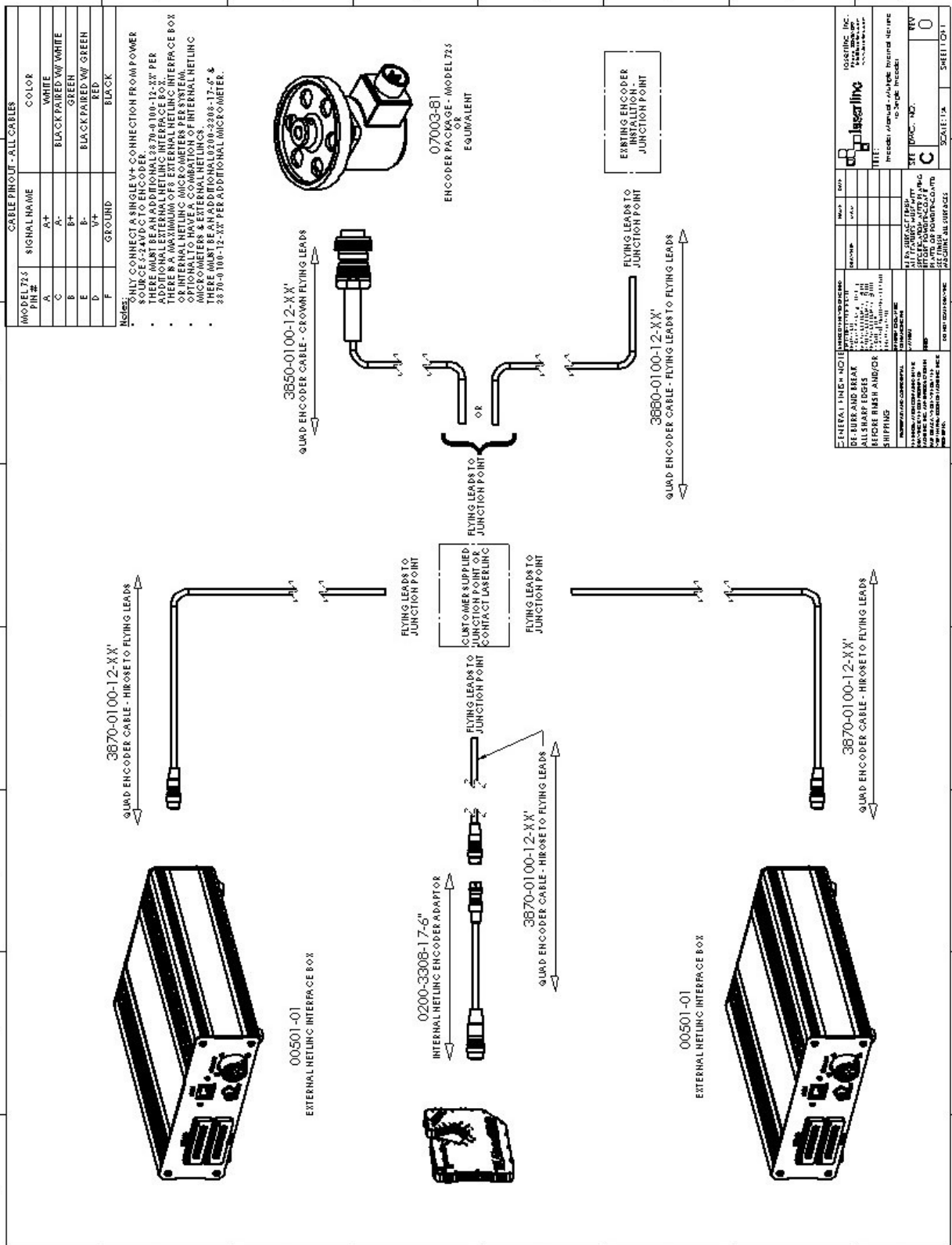
LaserLinc, Inc.
 Phone: 937.318.2440
 www.laserlinc.com

DRAWN BY:
 DATE:
 TITLE: Encoder (Internal) - Single micrometer to Single Encoder
 SIZE: DWG. NO.: B
 REV: 0
 SEE: 1 OF 1
 SCALE: 1:1

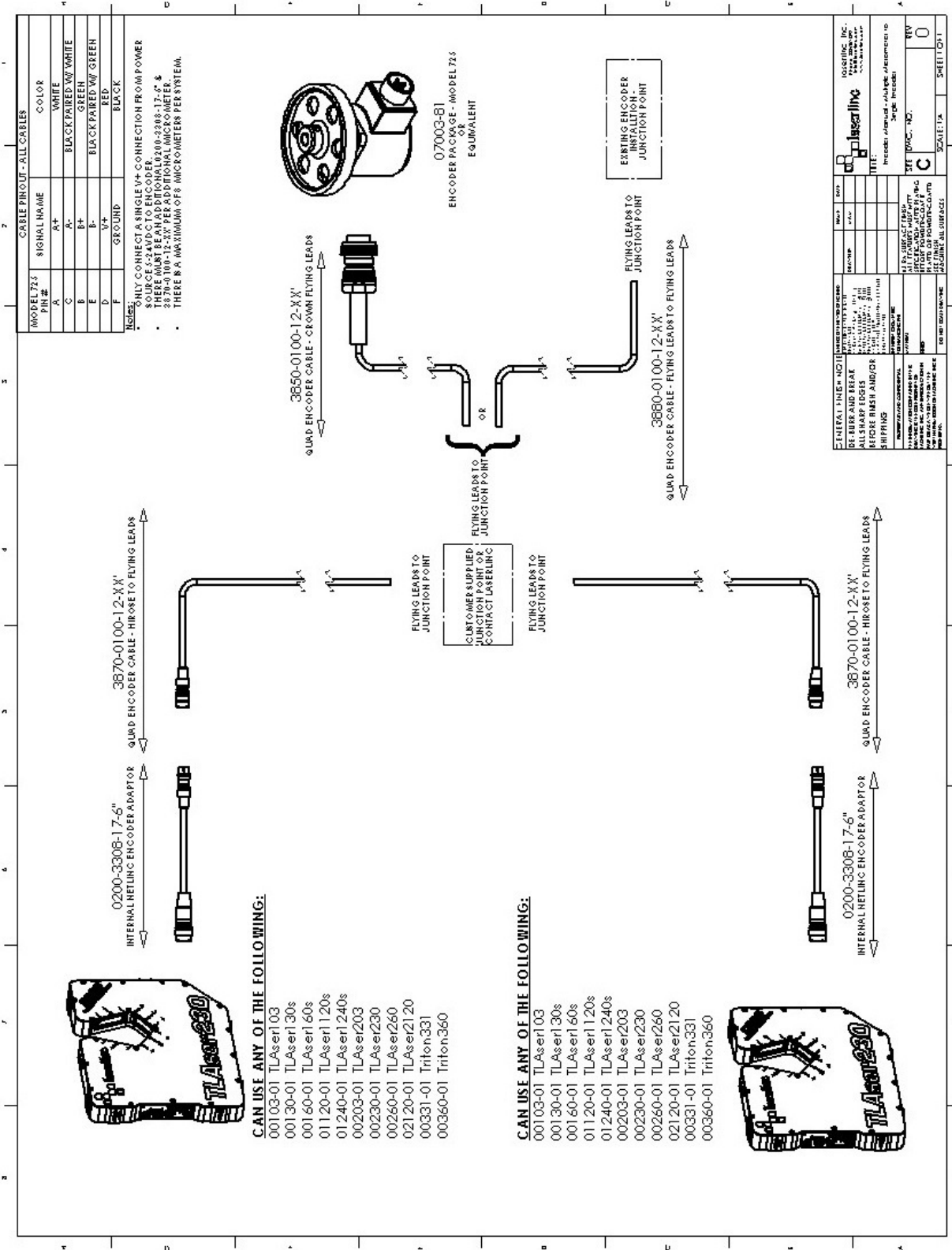
81 PA SURFACE FINISH SPECIFICATION: SEE FINISH SPECIFICATION WATER PLATING BEFORE POWDER-COATING PLATED OR POWDER-COATED SEE FINISH SPECIFICATION WATER PLATING BEFORE POWDER-COATING PLATED OR POWDER-COATED
 MACHINE ALL SURFACES



Typical Encoder Interface Wiring Diagram - External NetLinc
Diagram 3



Typical Encoder Interface Wiring Diagram - Multiple Ext/Int NetLinc(s)
 Diagram 4



Typical Encoder Interface Wiring Diagram - Multiple Internal NetLinc(s)
Diagram 5

Installation Procedure - NetLinc Internal or External Style

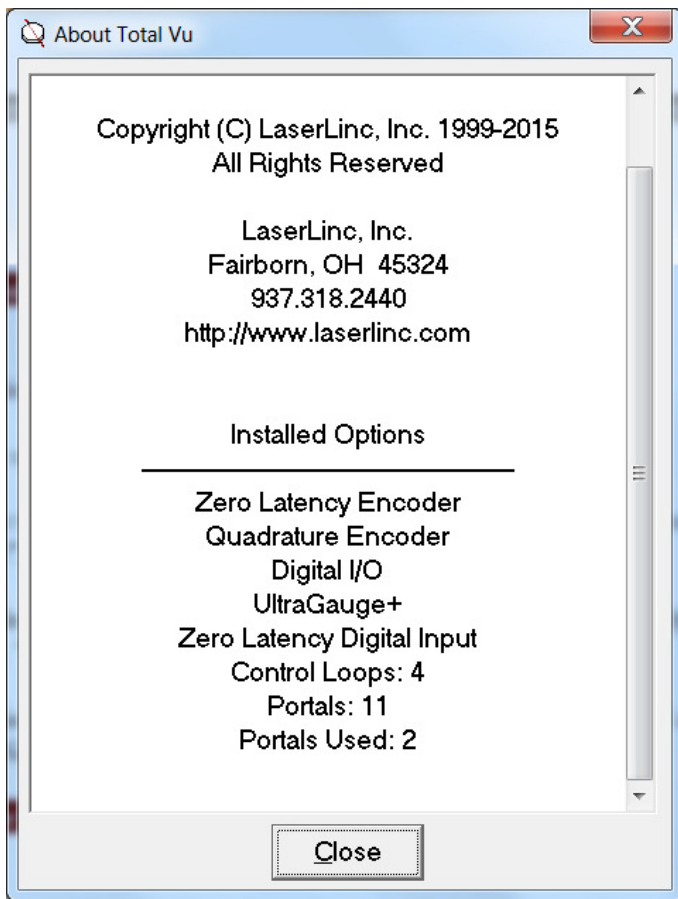
1. Ensure the *Encoder / Quadrature* option is added to your Total Vu software.
2. Internal NetLinc - Connect adapter cable PN 0200-3308-17-6" to LaserLinc scanner.
 - 2.1 Connect encoder interface cable to encoder pulse source. Connect 6 pin Hirose connector to adapter cable marked "Encoder". Proceed to Step 4.
3. External NetLinc - Connect encoder interface cable to encoder pulse source. Connect directly to the 6 pin Hirose connector marked "Encoder" on External NetLinc box.
4. Define an encoder in *Total Vu / Full Config / Encoders*. NOTE: The 1st encoder is predefined and assigned to either a TLAsEr400 or NetLinc encoder input. Measurement name is "*Length*".

Installation Procedure - PTRBe Counter Inputs

1. Add an encoder counter measurement in *Total Vu/Full Config/Encoders*. Upon selection of a counter (A0-D3), the connection pin-out within the Precision Timer Relay Enclosure (PTRBe) will be listed. Please note; this input is *non zero latency / non quadrature*, i.e., the count value IS NOT correlated to a measurement value, and counting is one direction only. The PTRBe is factory configured for (4) 5VDC encoder inputs only. Contact tech support should you need additional inputs or voltages.
2. Connect to the specified single-ended connection-point within the PTRBe enclosure using (2) wires from your encoder source - Signal & Ground, e.g., in the PTRBe enclosure, connect SIGNAL to TB31.1 (green terminal block) and GND to TP31.GND (blue push-button terminal).

Installation Procedure - Module on TLAser400 Card

Note: If you purchased the encoder option with your system, proceed to step 7.



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1. Power down the PC.
2. Remove the TLAs400 card.
3. Select desired signal input type.
 - 3.1 For single ended operation, remove jumper J4 on encoder module PCB (see assembly drawing - Diagram 9 below).
 - 3.2 For differential, install jumper J4 pins 1-2.

NOTE: refer to the data sheet for your particular encoder part number to determine this option.
4. Install the encoder module in channel 4 of the TLAs400 card.
Channel 4 is the SIMM module marked 'CH 4 J6' on the printed circuit board silkscreen.
5. Install/reinstall the PCI TLAs400 card.
6. Install the encoder input connector/PC bracket in any open rear panel slot.
 - 6.1 Tighten provided screws to secure connector.
7. Connect encoder using the provided encoder interface cable.
The leads are labeled and described in Table 3 (if connecting to your existing encoder output) or, plug directly into the LaserLinc supplied encoder.
8. Connect the encoder interface cable to the rear panel connector.
9. Ensure the *Encoder / Quadrature* option is added to your Total Vu Software.

TABLE 3 TLASER400 ENCODER SIGNAL DESCRIPTION

SIGNAL NAMES	DESCRIPTION	SIGNAL SOURCE
+5VDC/+12VDC Jumper J7 1-2 12V Jumper J7 2-3 5V	Used to provide power to the encoder. If encoder is already powered, these signals are not used . Insulate and tie-off leads.	TLAs400 card
Signal Ground (GND, GRD)	Reference signal for TLAs400 card. This must be connected to the encoder ground regardless of power source .	TLAs400 card
Encoder A (ENC A+) (DATA A)	Encoder output signal for single ended or positive half of differential signal pair.	Encoder
Encoder A' (ENC A-) (DATA A')	Encoder output signal for negative half of differential signal pair. If not used, then insulate and tie-off this lead.	Encoder
Encoder B (ENC B+) (DATA B)	Encoder output signal for single ended or positive half of differential signal pair. Use for quadrature operation.	Encoder
Encoder B' (ENC B-) (DATA B')	Encoder output signal for negative half of differential signal pair. Use for quadrature operation.	Encoder

Encoder Connection

The LaserLinc encoder interface connects to encoders from many different manufactures. Please refer to your particular encoder data sheet for pin-out information. **FAILURE TO CONNECT THE ENCODER PROPERLY MAY RESULT IN DAMAGE TO THE ENCODER INTERFACE, TLAsEr400 CARD, NETLINC, PTRBe AND ENCODER!**

Depending on what encoder output options are selected, your encoder may require pull-up resistors. Consult your encoder manufacturer’s data sheet for details. Failure to use pull-up resistors when needed will prevent the encoder from generating pulses. No damage will occur. Pull-up resistors may be added to the encoder interface module. Contact LaserLinc technical support for details: 937-318-2440.

1 Choose a method for encoder interfacing.

The power is supplied to the encoder from either the TLAsEr400 encoder interface, NetLinc, or the encoder is already powered by another device.

1.1 If the encoder is powered by another device, determine the voltage level that is used.

The TLAsEr400 & NetLinc encoder interfaces are factory-set to accept signals up to 28V. The PTRBe is factory configured for 5VDC operation only. Voltage inputs up to 28VDC are available, contact LaserLinc tech support.

TABLE 4 BACKPANEL HIROSE CONNECTOR PIN OUT

WIRE LEAD	CONNECTOR	ENCODER FUNCTION
ENC A'	PIN 1	Signal \tilde{A} (line over A) (optional, install jumper J4 1-2 (default) on TLAsEr400 encoder interface if used—enables differential signal)
ENC B	PIN 2	Signal B (Use for quadrature only)
ENC B'	PIN 3	Signal B' (Use for quadrature only)
GRD	PIN 4	Supply Common (must use)
+5VDC/+12VDC	PIN 5	Power Source (if used, select with jumper J7)
ENC A	PIN 6	Signal A (must use)

Encoder Operation

You must first have Total Vu software and a scanner installed with a measurement configured.

1. Hit <F2> or click the **Start** button.
2. Right click in any measurement window (or create a new window).
3. Select **Properties** then **Measurement** tab.
4. Select the **Length** measurement and **Add**. Click **OK**.
5. Turn the encoder shaft.
6. The **Length** field should count up as the encoder is turned. Refer to the *Total Vu User's Guide* for further application setup.
7. To calibrate your encoder, determine the number of pulses per <desired unit of measure>. Enter values into the encoder configuration in **Full Config / Encoders**.

Encoder Configuration - Length

General | Encoder | Length Measurement | Speed Measurement | Use as Default

Length Measurement Name
Enter the name for the length measurement. It must begin with a letter or a digit. [] or | are illegal. The name may be up to 30 characters in length and it must be unique.

Length

Units
Select the units represented by the encoder count.

Feet

Pulses per Foot
Enter the number of pulses that equal one Foot of movement.

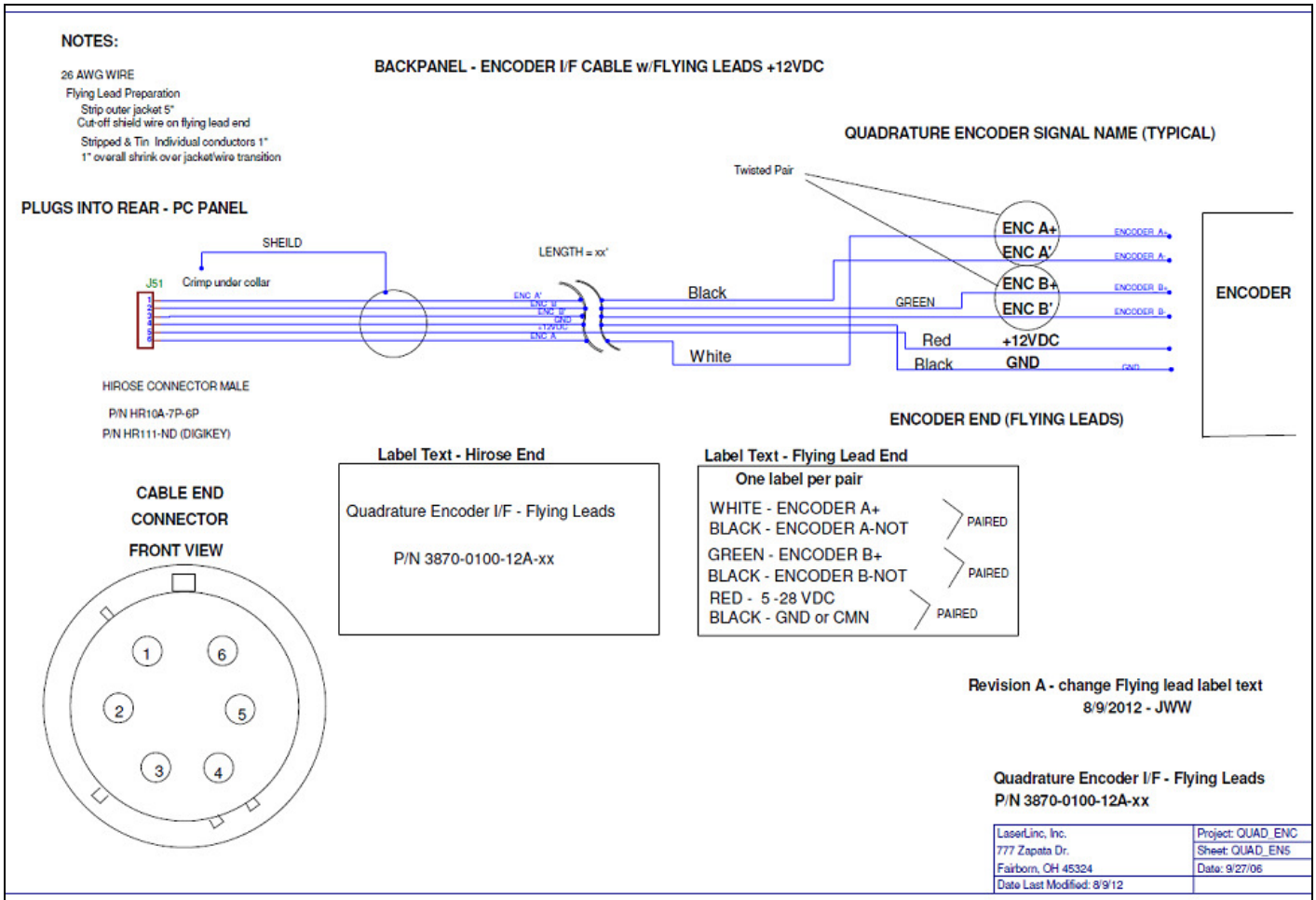
1000

Resolution
Select the number of places to display in the measurement value to the right of the decimal point.

1 0.1

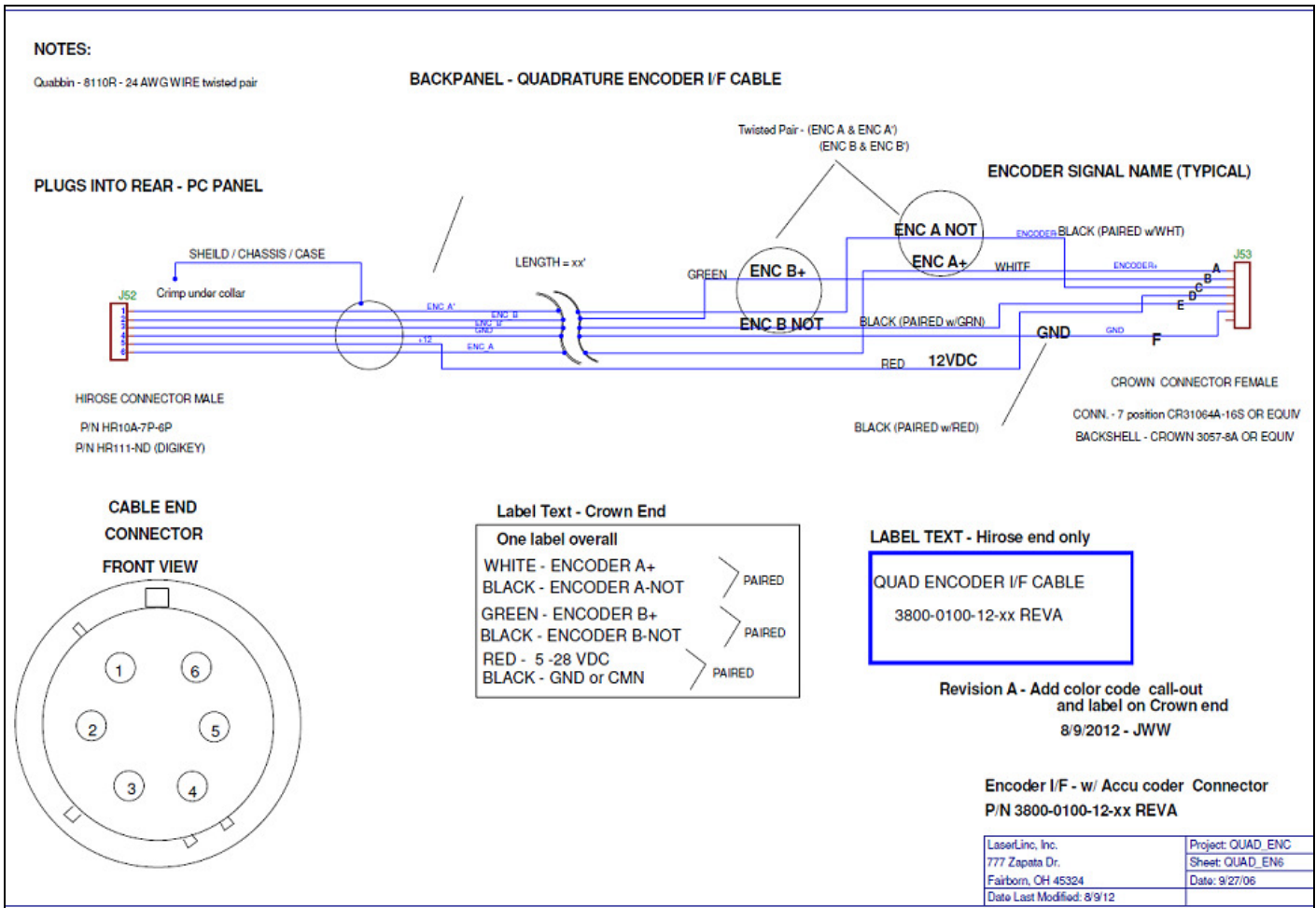
OK Cancel

QUADRATURE ENCODER INTERFACE SPECIFICATION AND INSTALLATION GUIDE



Flying Lead Cable Schematic (Hirose to flying lead)
 Diagram 6

QUADRATURE ENCODER INTERFACE SPECIFICATION AND INSTALLATION GUIDE



Direct Encoder Cable Schematic (Hirose to Crown)
 Diagram 7

Encoder Pin Out - Encoder Products Inc. Model 725-NSS1000AHV1FNsyn

TABLE 5 SAMPLE OPTICAL ENCODER WIRING FOR MODEL 725 FROM ENCODER PRODUCTS CO.

ENCODER PIN	FUNCTION	LASERLINC CONNECTION
A	DATA A	Signal A / Encoder A+
B	DATA B	Signal B / Encoder B+
C	DATA A'	Signal A'/Encoder—Use alone (along with GND) if encoder module on TLAsr400 Card has Jumper J4 removed
D	+ VOLTS DC	5 - 28VDC
E	DATA B'	Signal B' / Encoder B-
F	COMMON	Ground
G	CASE	Shield optional

Encoder Mechanical Drawing

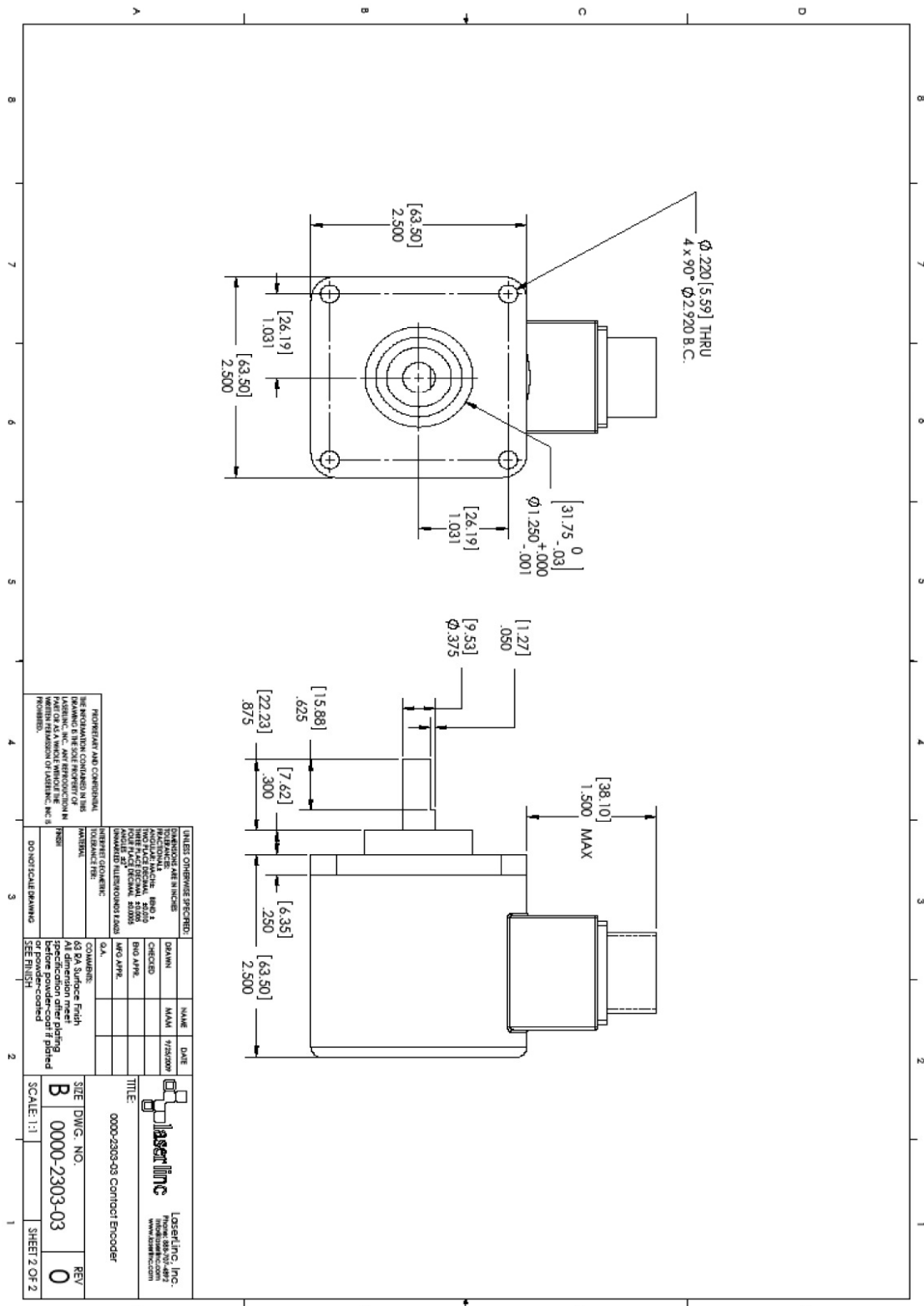
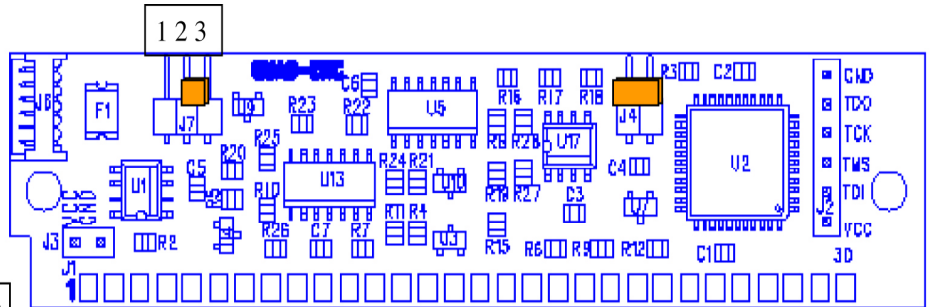


Diagram 8

TLAser400 Encoder Module - Jumper Settings



Default Jumper Settings
 J7 – 2-3 (5V)
 J4 – Installed (differential)


LaserLinc INC.		777 Zapata Dr. Fairborn, OH 45324 937-318-2440	
QUADRATURE ENCODER		RS274X FORMAT, ASCII, ABSOLUTE	
Board No.: 3800-1105-01		3 INTEGER DIGITS	
REV: A		5 FRACTIONAL DIGITS	
PRIMARY ASSEMBLY		LAYERS VIEWED FROM	
 CDC Technologies Inc.		PRIMARY SIDE	
PHONE # (937) 898-8713 FAX # (937) 898-8715		DATE: 1/26/07	
WWW.CDCTECHINC.COM		CDC JOB NO.: CDC1362	

Diagram 9